

Produções científicas:

- *LARS 2022: MPC-Based Reference Governor Control for Self-Righting of Quadruped Robots: Preliminary Results:*

Link da publicação: <https://ieeexplore.ieee.org/document/9995759>

Vencedor do melhor artigo: <https://fei.edu.br/robotica/lars-sbr/>

15 BEST PAPERS

The list below presents the 15 best papers selected (out of the 80 submissions) to be invited for submission of an extended version to the Journal of Intelligent & Robotics Systems (IJRS)

Paper Title	Authors
MPC-Based Reference Governor Control for Self-Righting of Quadruped Robots: Preliminary Results	Aureo Dobnikopf (Universidade do Estado de Santa Catarina - Brazil), Lucas Schulze (Universidade do Estado de Santa Catarina - Brazil), Douglas Bertol (Universidade do Estado de Santa Catarina - Brazil), Victor Barasuol (Istituto Italiano di Tecnologia - Italy)